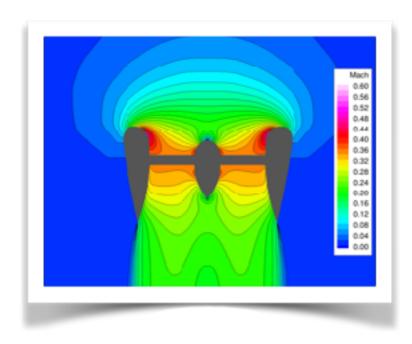




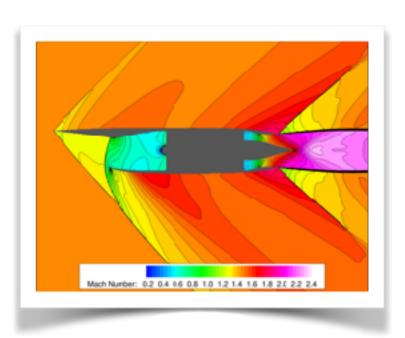
Formulation and Implementation of Inflow/Outflow Boundary Conditions to Simulate Propulsive Effects



David L Rodriguez Michael Aftosmis Marian Nemec

> January 8, 2018 SciTech 2018

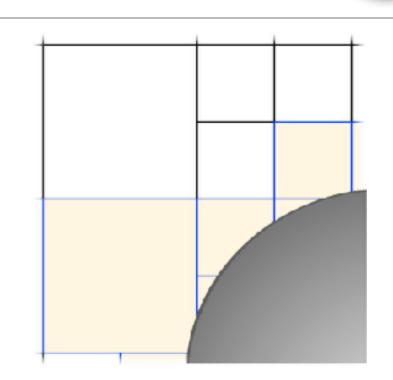
NASA Ames Research Center

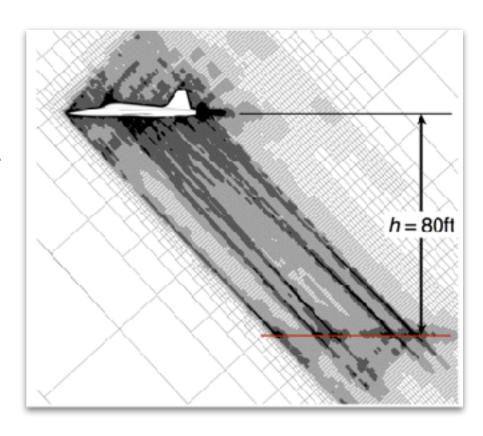


Cart3D Aerodynamic Analysis & Design Package



- Automated multilevel Cartesian mesh generation with adjoint-driven adaptive refinement
- Cut-cell approach in cells that include model surface
- Finite volume, 2nd-order accurate Euler solver with explicit Runge-Kutta time stepping and multigrid
- Steady or time-accurate
- Part of a design framework allowing for gradientbased aerodynamic shape optimization of userspecified functional
- Shown to be highly effective for analysis and design of low boom aircraft



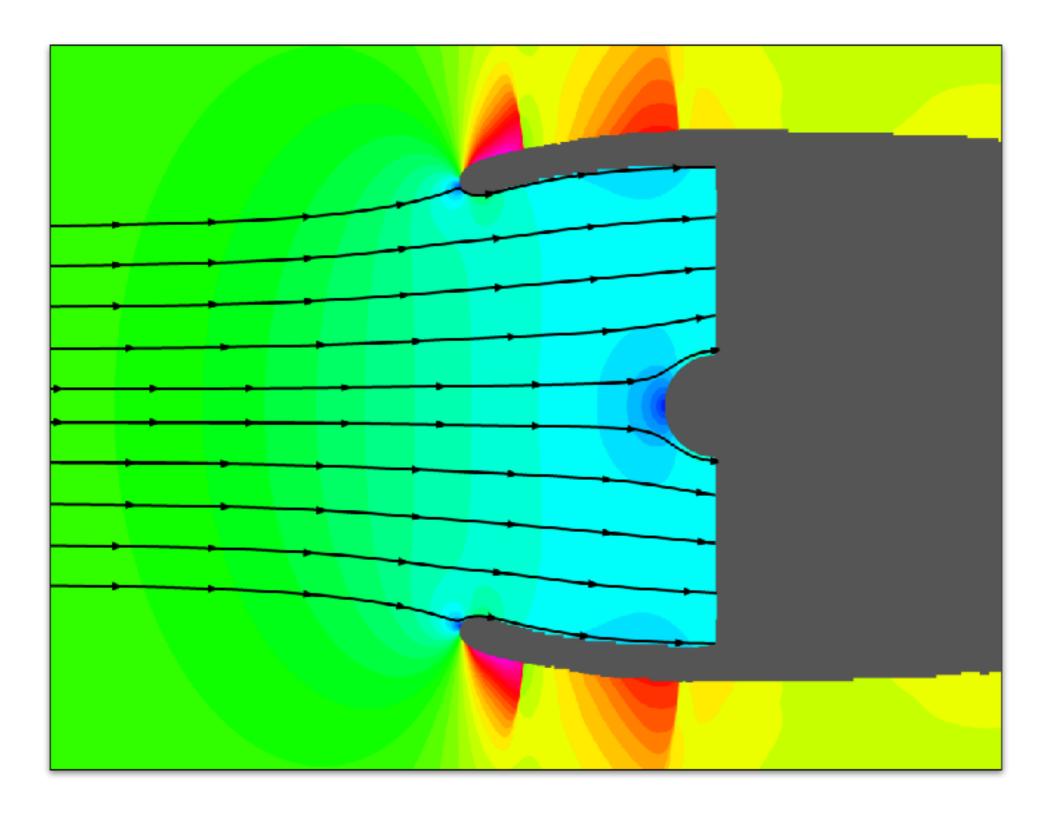


Motivation for New Boundary Conditions



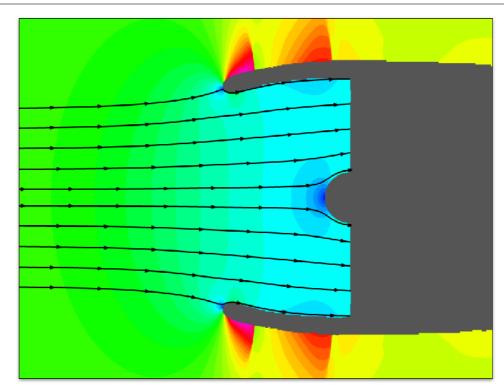
- Current **SurfBC** inflow/outflow boundary condition requires user to specify an entire state (ρ, U, V, W, p) at the boundary
 - Riemann solver is applied to compute flux at the boundary and thus boundary condition is always well-posed
 - Robust and flexible since it can be used for both inflow and outflow, subsonic and supersonic
- Inconvenient when user wants to specify inflow or outflow with minimal information
 - for subsonic flow through inlets, most common boundary condition is back pressure
 - for subsonic flow into nozzles, most common boundary condition is specifying total pressure and total temperature (and flow direction)
 - very difficult to specify mass flow rate, particularly in cases where nonlinear flow features are prevalent

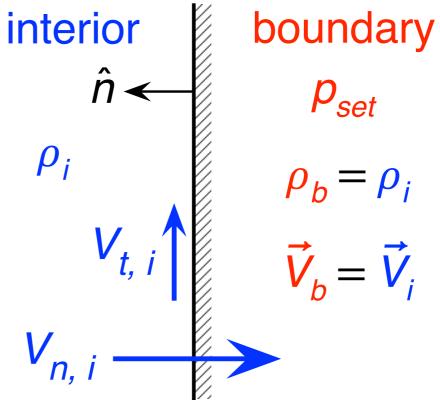






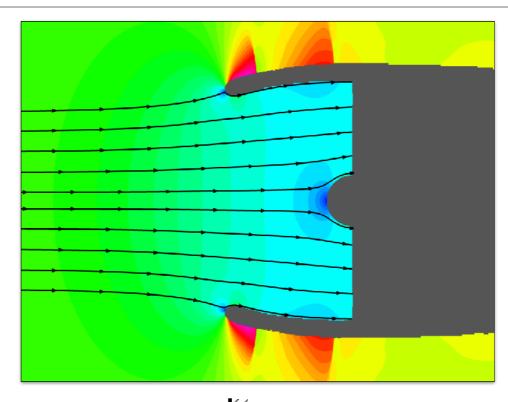
- CFL3D
 - set pressure
 - extrapolate density and velocity

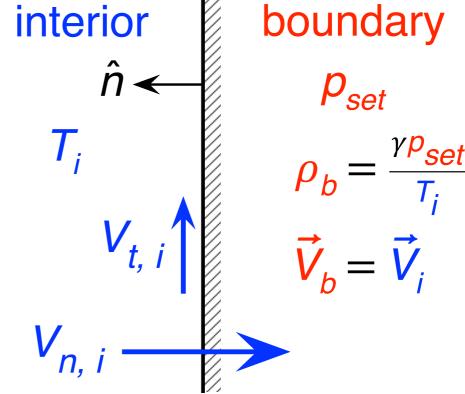






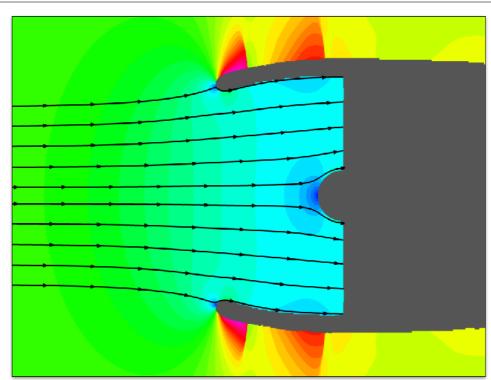
- CFL3D
 - set pressure
 - extrapolate density and velocity
- Fun3D
 - set pressure
 - extrapolate velocity and temperature
 - update density

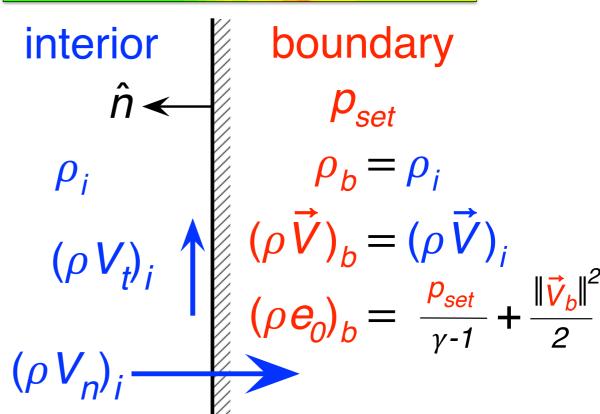






- CFL3D
 - set pressure
 - extrapolate density and velocity
- Fun3D
 - set pressure
 - extrapolate velocity and temperature
 - update density
- OVERFLOW
 - set pressure
 - extrapolate density and momentum
 - update total energy

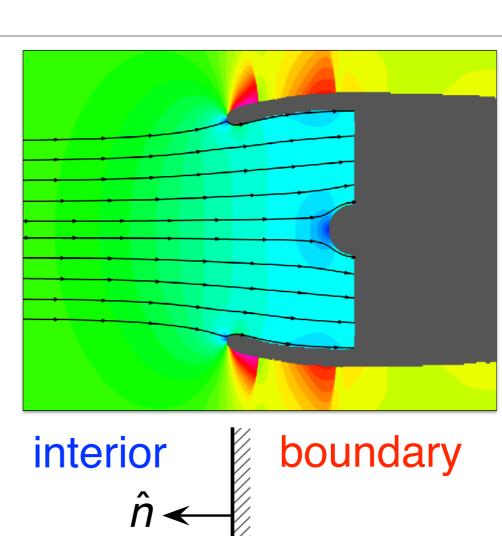






• CFL3D

- set pressure
- extrapolate density and velocity
- Fun3D
 - set pressure
 - extrapolate velocity and temperature
 - update density
- OVERFLOW
 - set pressure
 - extrapolate density and momentum
 - update total energy
- Cart3D (since 2004)
 - set entire boundary flow state
 - Riemann solver applied



 $\hat{\rho}_i$ $\hat{\rho}_{set}$

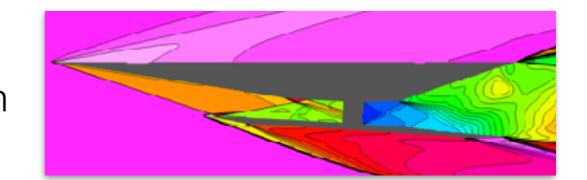
 p_{se}

 $ec{V}_{set}$

Cart3D Surface Boundary Conditions



- Solid wall
- Specify full flow state and use Riemann solver (SurfBC)



- Pandya, Murman, Aftosmis, 2004
- for all inflows and outflows

Cart3D Surface Boundary Conditions

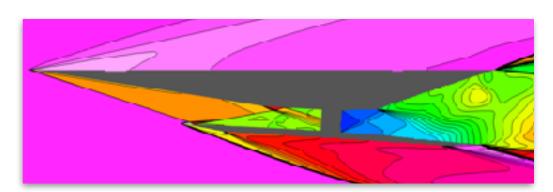


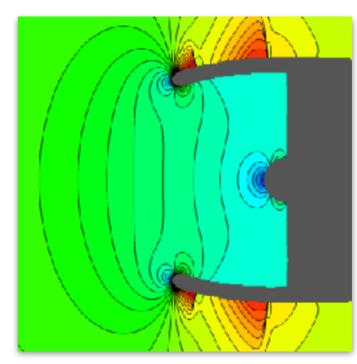
- Solid wall
- Specify full flow state and use Riemann solver (SurfBC)
 - Pandya, Murman, Aftosmis, 2004
 - for all inflows and outflows
- Subsonic Outflow
 - back pressure



constant normal velocity







Cart3D Surface Boundary Conditions



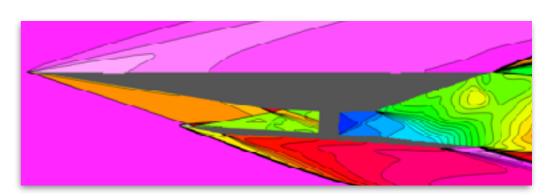
- Solid wall
- Specify full flow state and use Riemann solver (SurfBC)
 - Pandya, Murman, Aftosmis, 2004
 - for all inflows and outflows
- Subsonic Outflow
 - back pressure

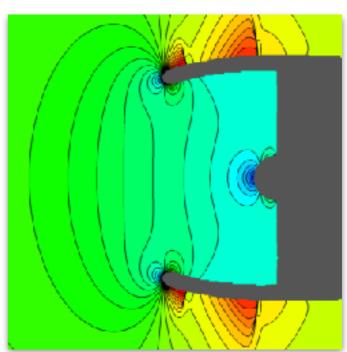


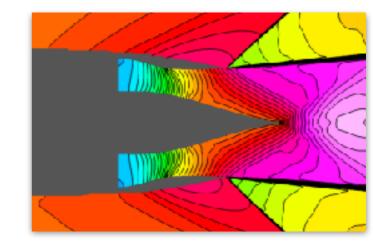
- constant normal velocity
- Subsonic Inflow
 - total pressure and total temperature



mass flow rate and total temperature



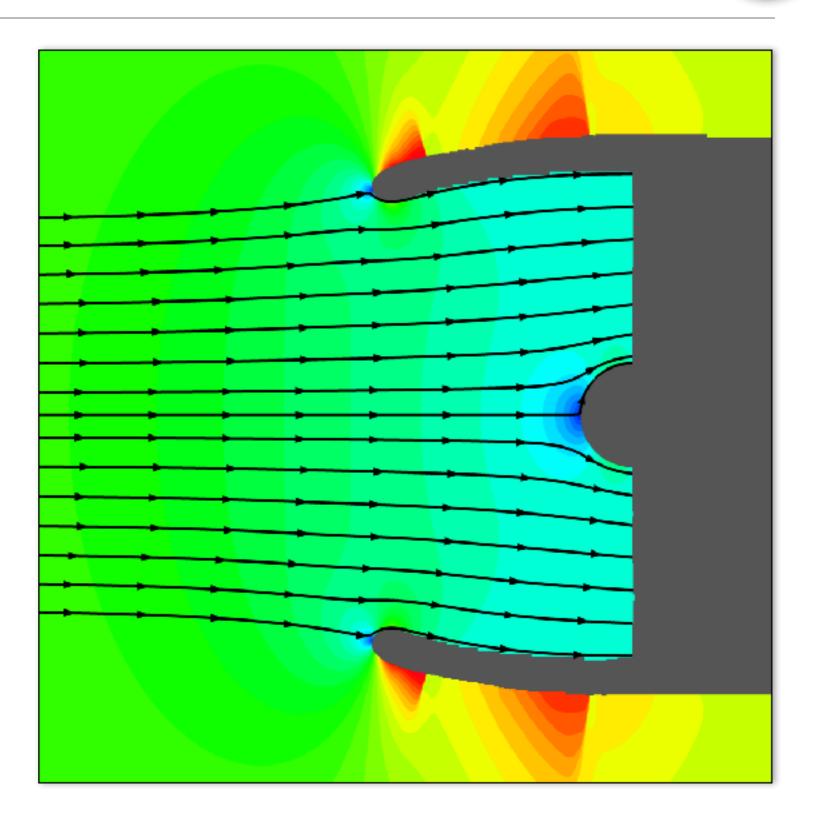




Subsonic Outflow Boundary Conditions



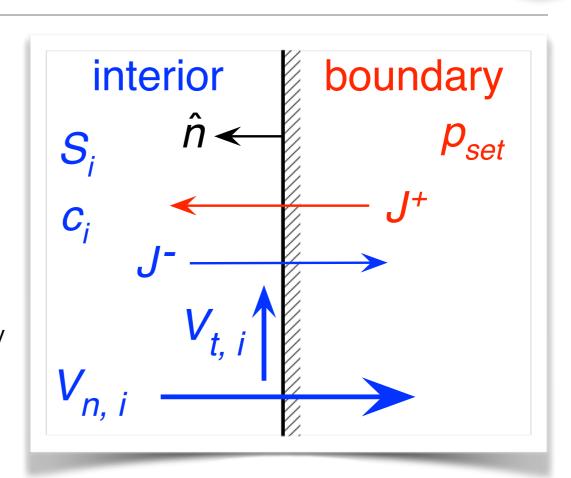
- One flow quantity specified at boundary
 - back pressure
 - normal velocity
- Four flow quantities extrapolated from interior



Back Pressure Outflow



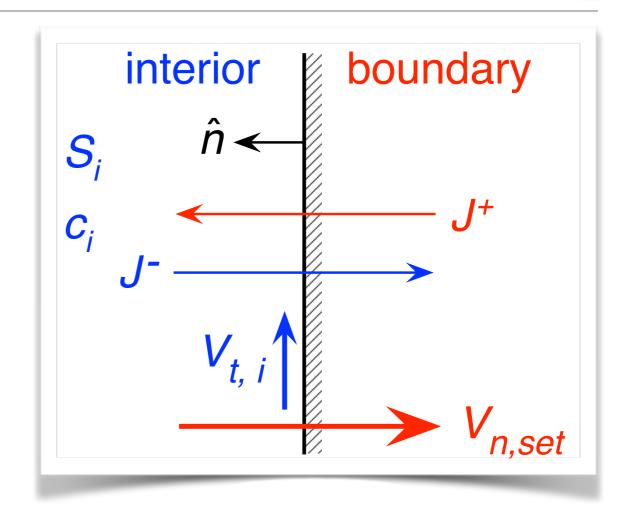
- Most other CFD solvers have this common option
- Pressure set to specified value at boundary
- Entropy and tangential velocity extrapolated from interior
- Riemann invariants used to compute boundary state
- Safeguards
 - · if flow reverses back into interior (back pressure too high), solid wall boundary enforced
 - if interior flow goes supersonic, compare back pressure to pressure after normal shock occurring at boundary
 - if set back pressure is higher, use after-shock state at boundary, forcing subsonic flow in the interior
 - if set back pressure is lower, extrapolate all flow attributes from interior (supersonic outflow)
- Can be difficult to obtain specific mass flow rate for nonlinear flows



Constant Normal Velocity Outflow



- Allows for robust mass flow rate steering
- Might better represent flow in front of an engine fan face (Pearson '59, Reid '69)
- Normal velocity set to specified value at boundary
- Entropy and tangential velocity extrapolated from interior
- Riemann invariants used to compute boundary state



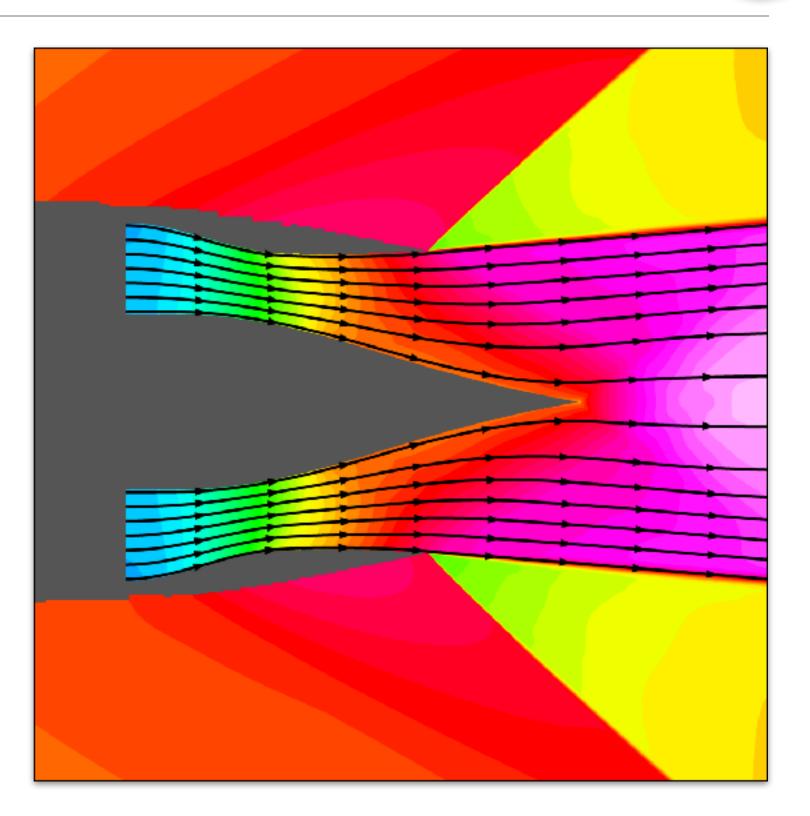
Safeguards

- when interior flow is subsonic but boundary flow is supersonic (bad input velocity), flow is forced to be sonic (choked flow)
- when interior and boundary flow are both supersonic, supersonic outflow is enforced (all interior quantities extrapolated)

Subsonic Inflow Boundary Conditions



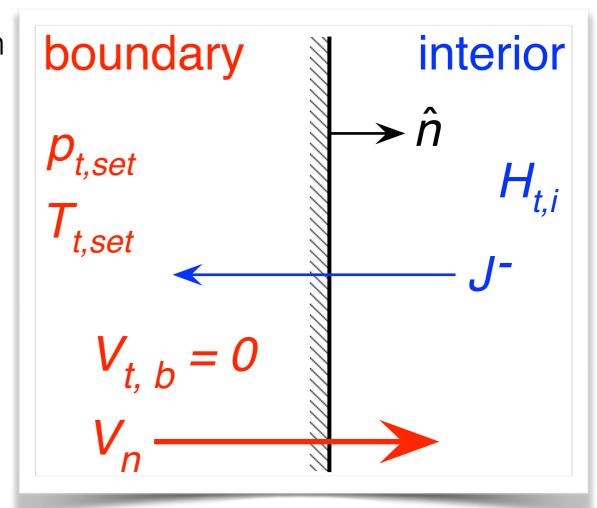
- Four flow quantities specified at boundary
 - velocity set to be normal to boundary (two flow quantities)
 - total pressure and total temperature
 - mass flow rate and total temperature
- One flow quantity extrapolated from interior



Stagnation Property Inflow



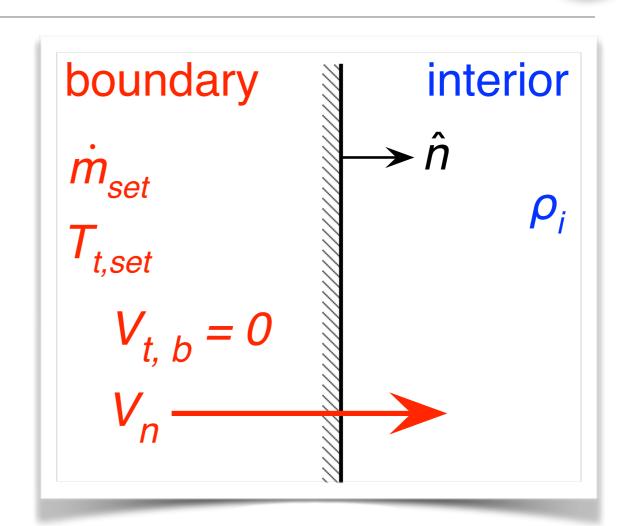
- Most other CFD solvers have this common option
- Total pressure and temperature set to specified value at boundary
- Tangential velocity set to zero, forcing inflow to be normal to surface
- Enthalpy is extrapolated from interior
- Riemann invariant used to computed boundary state
- Safeguards
 - when flow tries to reverse back into boundary, solid wall boundary enforced
 - inflow Mach number is limited to sonic, adjusting stagnation properties accordingly
- Cannot explicitly set a mass flow rate



Mass Flow Rate and Total Temperature Inflow

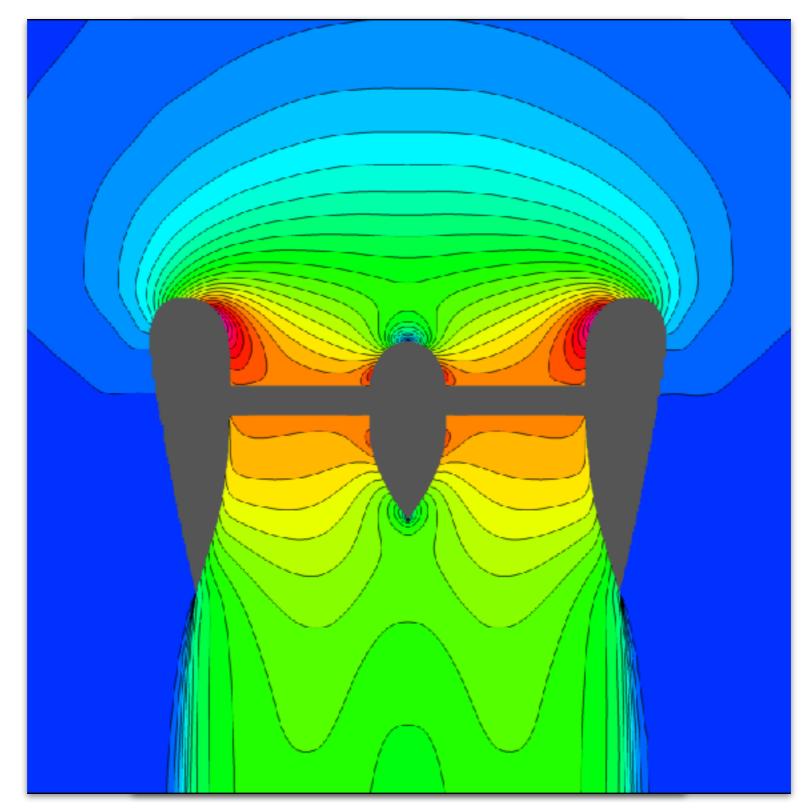


- Allows for explicit mass flow rate control
- Mass flow rate and total temperature set to specified value at boundary
- Tangential velocity set to zero, forcing inflow to be normal to surface
- Density is extrapolated from interior
- Boundary flux computed from boundary state
- Safeguard
 - inflow Mach number is limited to sonic, adjusting boundary values accordingly



Mass Flow Rate Control

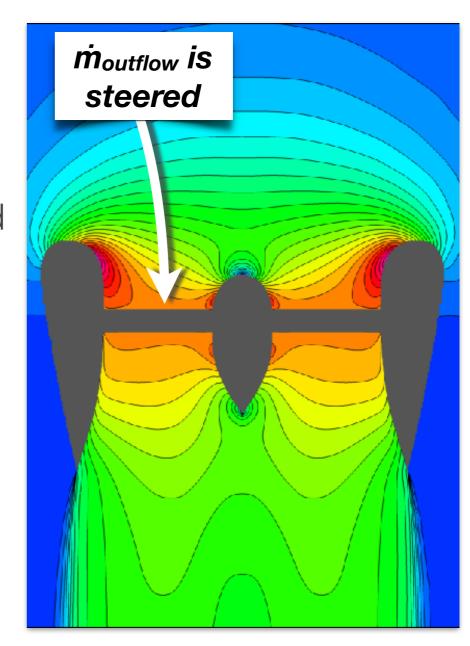




Mass Flow Rate Control



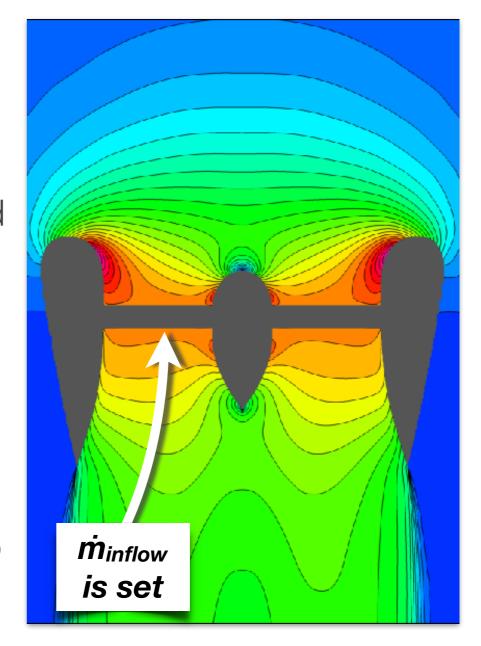
- Constant velocity outflow boundary condition can be steered to obtain specified mass flow rate out of the domain
 - average density over surface is computed
 - velocity out of domain is set based on desired mass flow rate
 - repeat every few iterations until solution converged and mass flow rate within tolerance



Mass Flow Rate Control



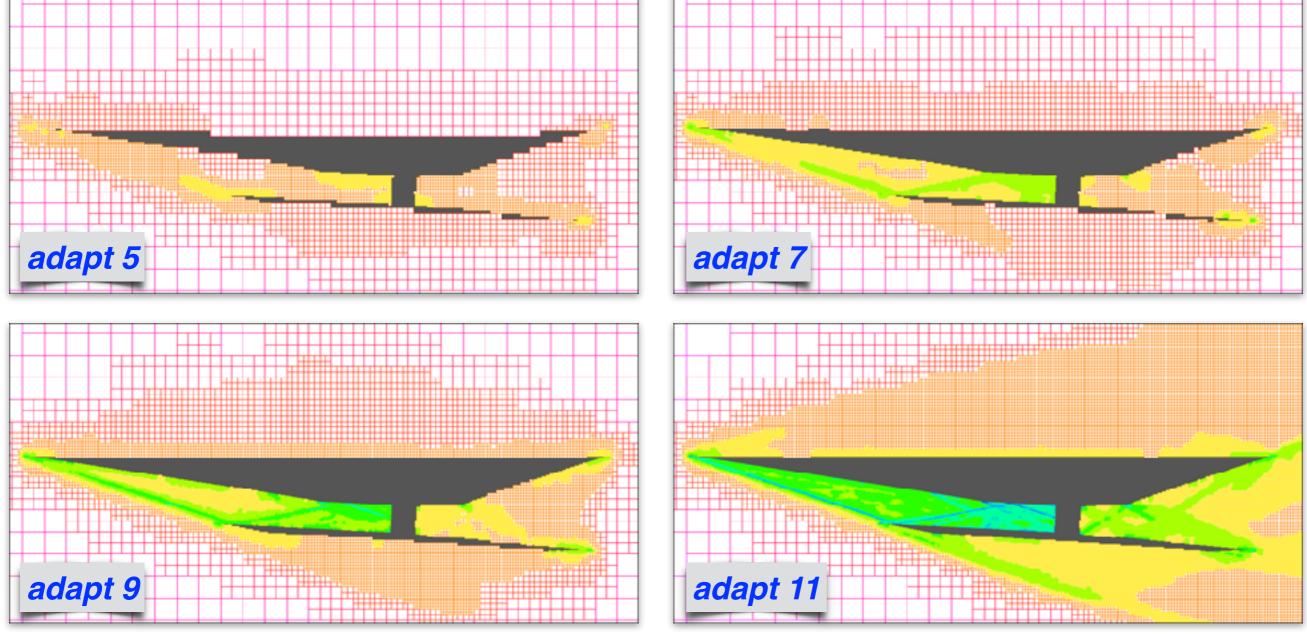
- Constant velocity outflow boundary condition can be steered to obtain specified mass flow rate out of the domain
 - average density over surface is computed
 - velocity out of domain is set based on desired mass flow rate
 - repeat every few iterations until solution converged and mass flow rate within tolerance
- Constant mass flow rate inflow boundary condition explicitly sets mass flow rate into the domain



Adjoint-Driven Adaptive Mesh Refinement



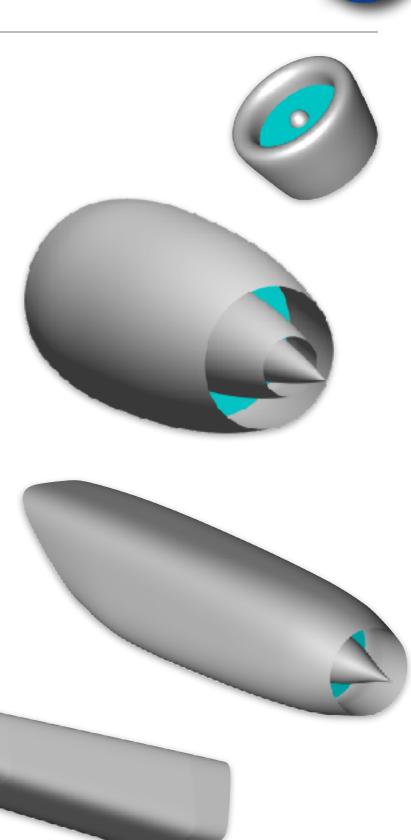
- All boundary conditions now implemented in adaptive mesh refinement process
- Updates to adjointCart, xSensit, adjointErrorEstQuad, etc.



Application of New Boundary Conditions



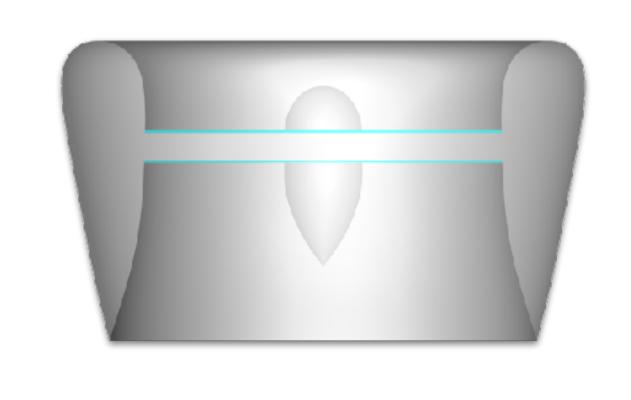
- Ducted fan in near-hover (subsonic)
 - verification of back pressure outflow and mass flow rate inflow boundary conditions
- Turbofan with both fan and turbine exhaust streams (transonic)
 - verification of constant velocity outflow boundary condition
- Turbojet with 2-D ramp inlet (supersonic)
 - mesh convergence through adaptive refinement
 - mass flow rate steering example
- Scramjet (hypersonic)
- Low boom demonstrator

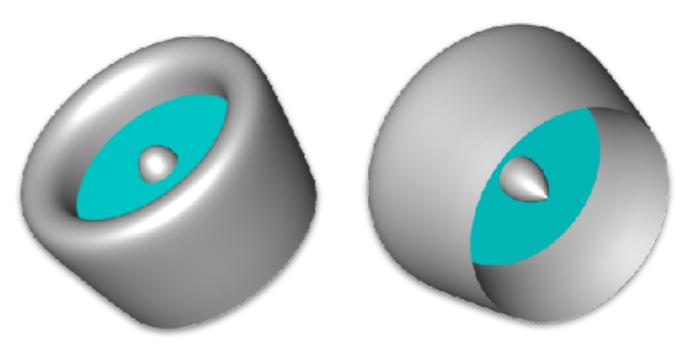


Ducted Fan in Hover



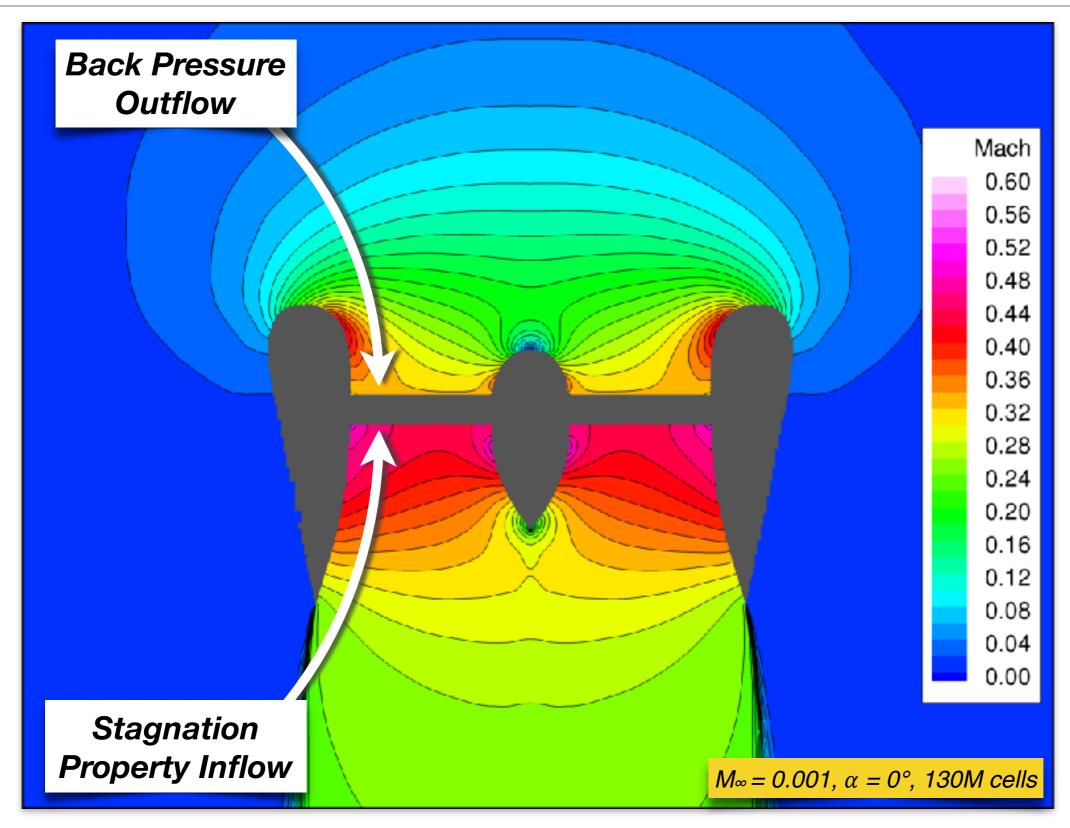
- Duct and center body housing motor to drive fan
- Very low freestream Mach number (0.001) to simulate near hover
- No angle of attack axisymmetric flow
- Fan modeled as annular disk
- Inflow / Outflow boundary conditions enforced on disk to model fan effects





Ducted Fan - Example Solution

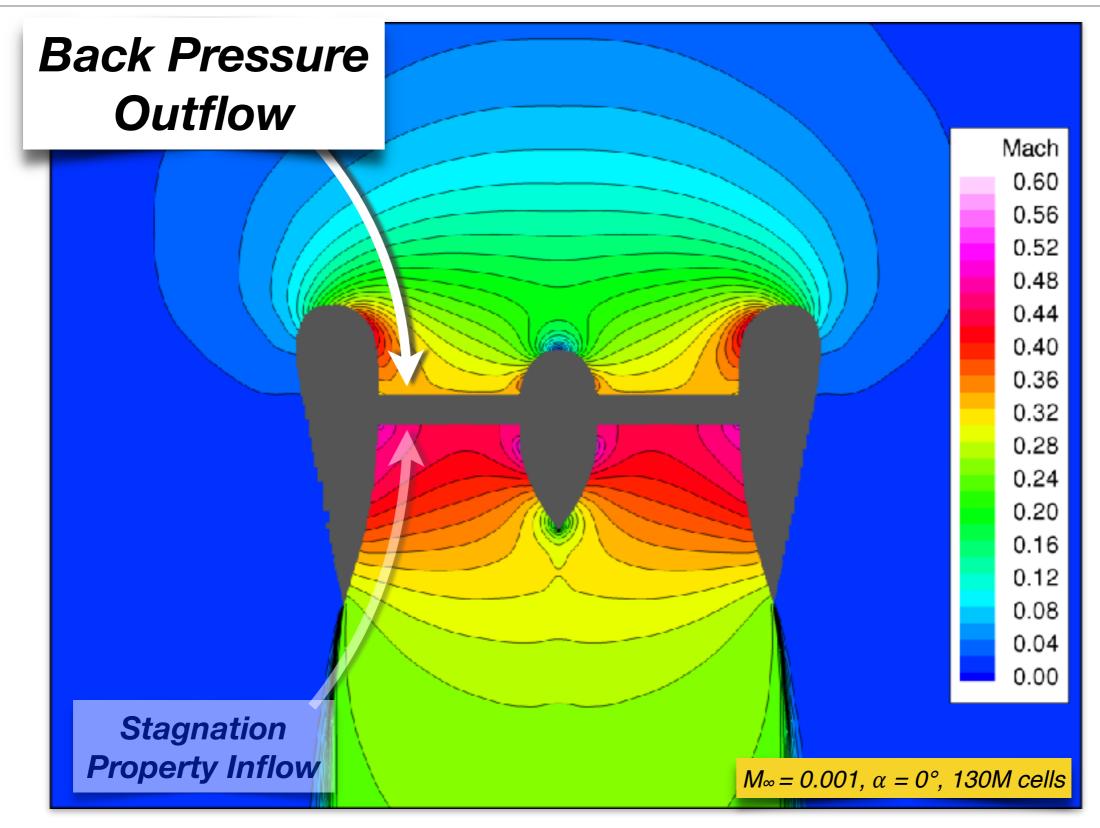




Ducted Fan - Example Solution

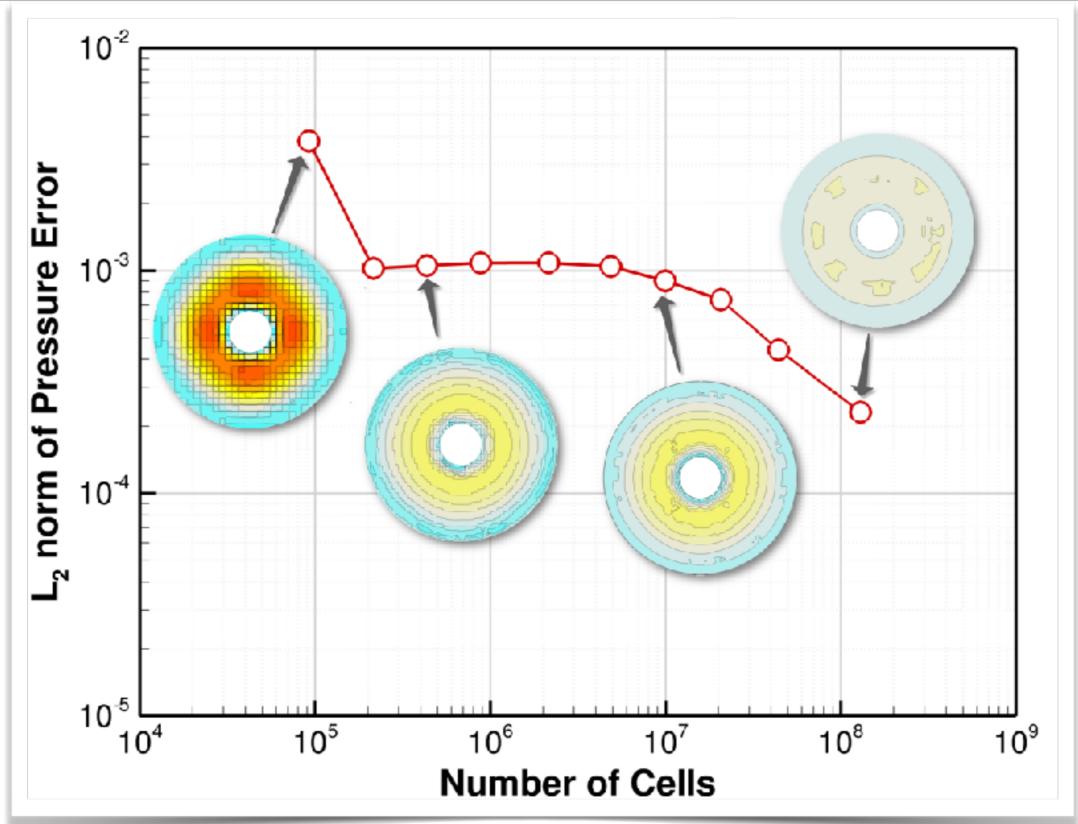


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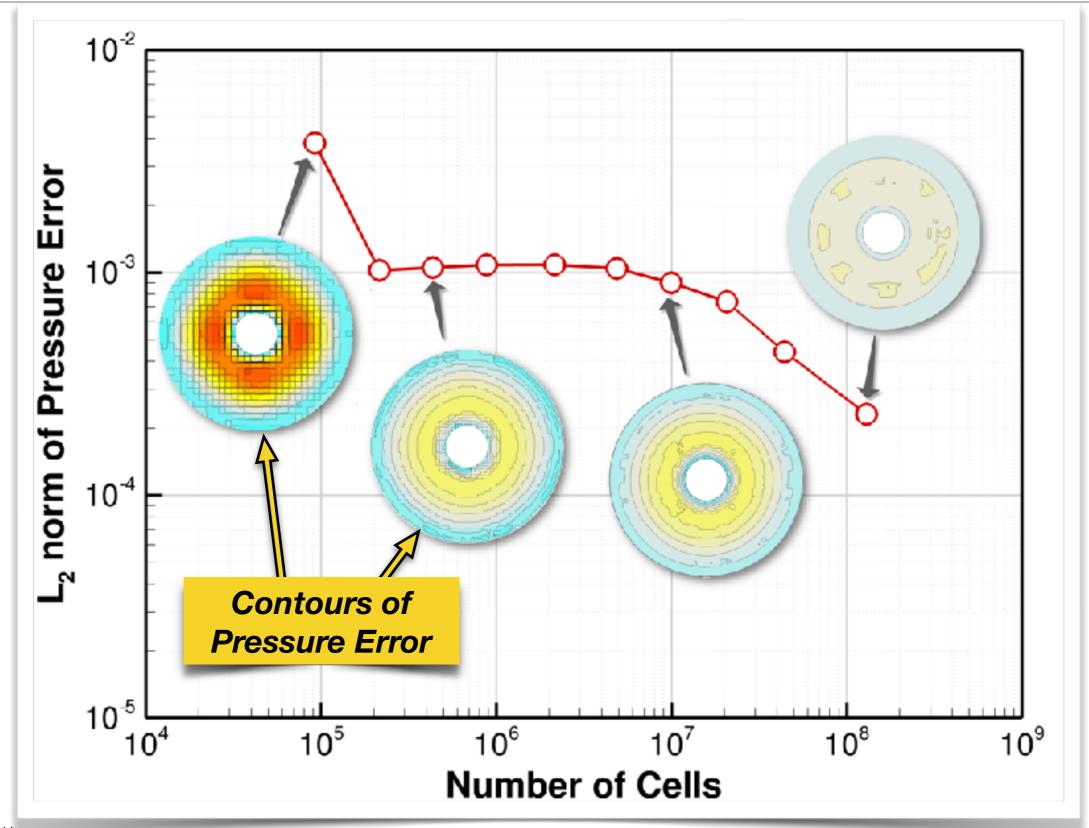
Back Pressure B.C. Mesh Convergence





Back Pressure B.C. Mesh Convergence

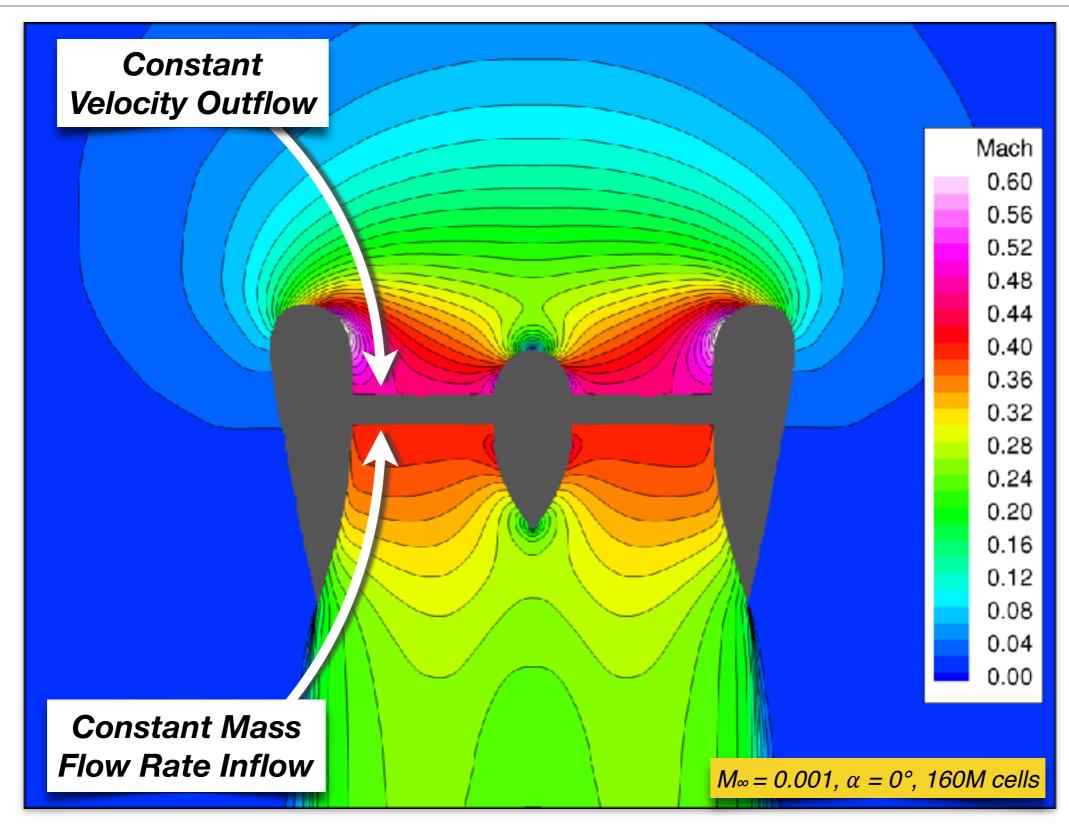




Ducted Fan - Example Solution

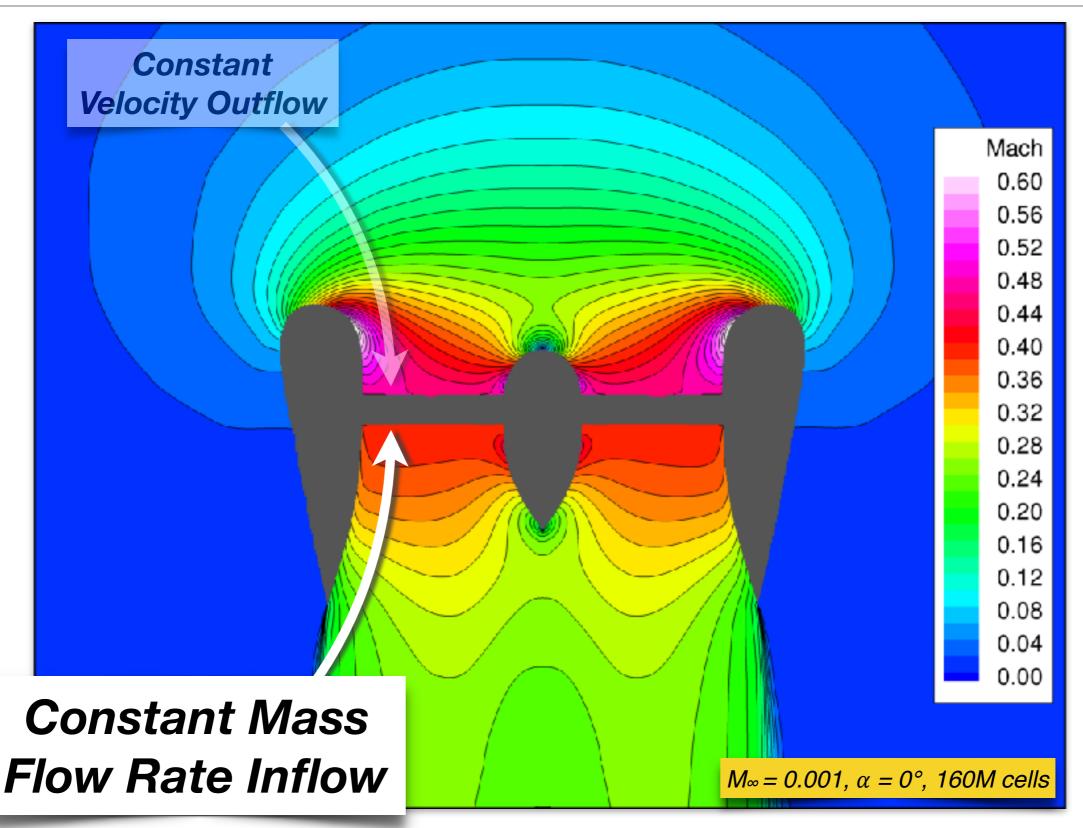


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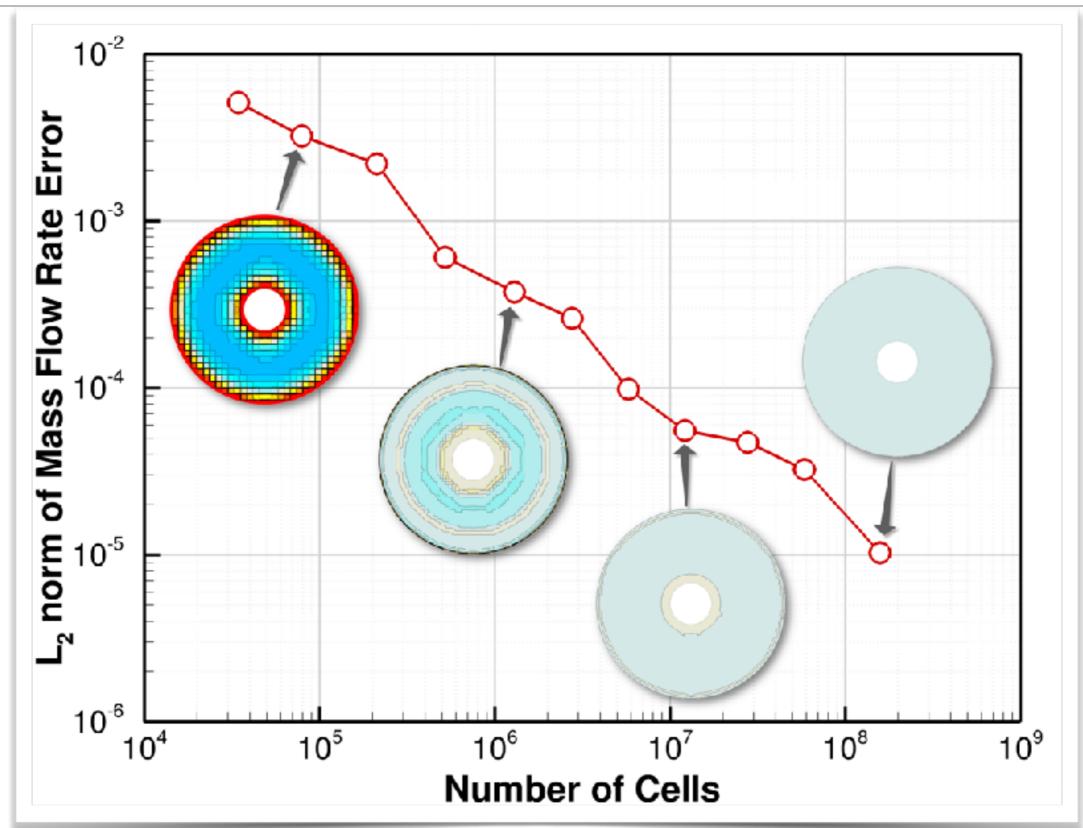
Ducted Fan - Example Solution





Constant Mass Flow Rate B.C. Mesh Convergence

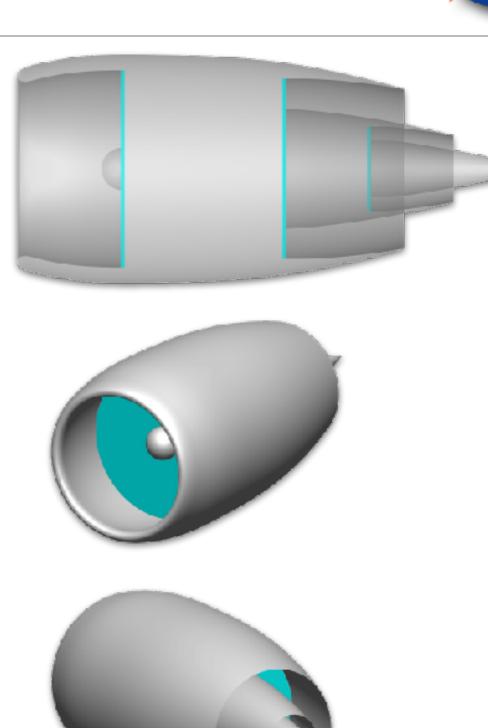




Turbofan in Transonic Flow

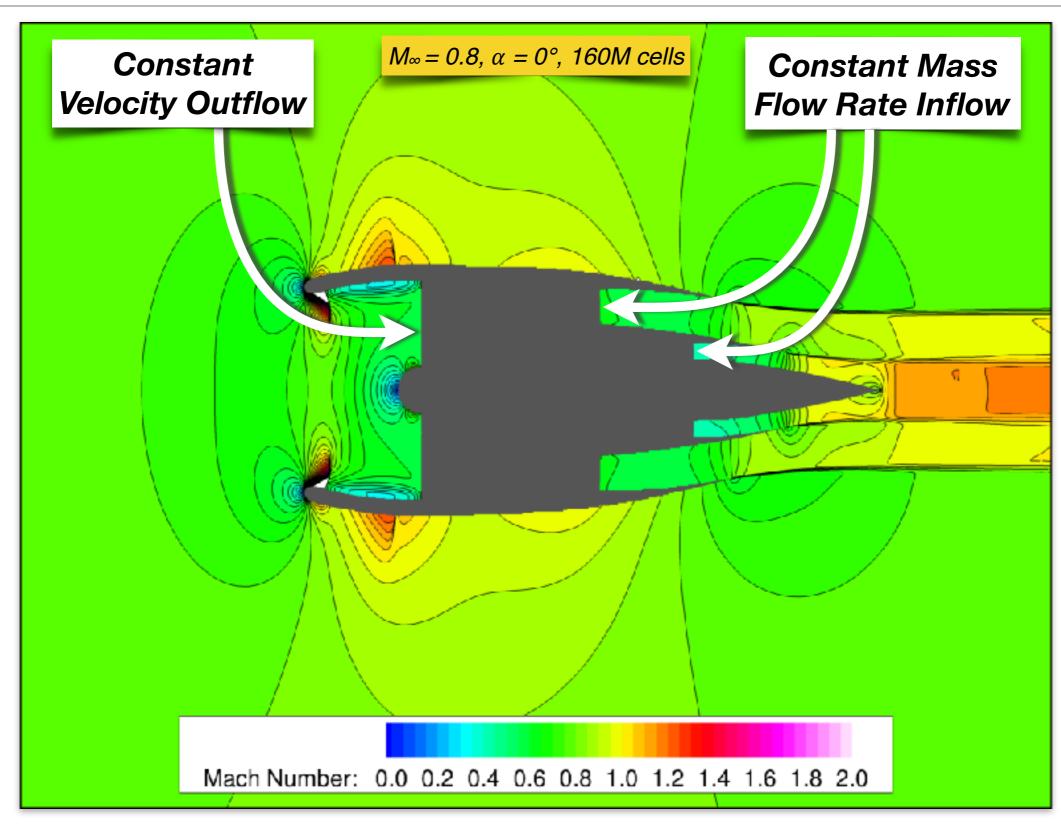


- Transonic diffuser with fan hub
- Two stream exhaust with cone nozzle for turbine flow
- Mach 0.8 freestream, no angle of attack (axisymmetric flow)
- Fan / Compressor face modeled as annulus, outflow boundary condition applied
- Fan and turbine exhaust planes modeled as annuli, inflow boundary conditions applied



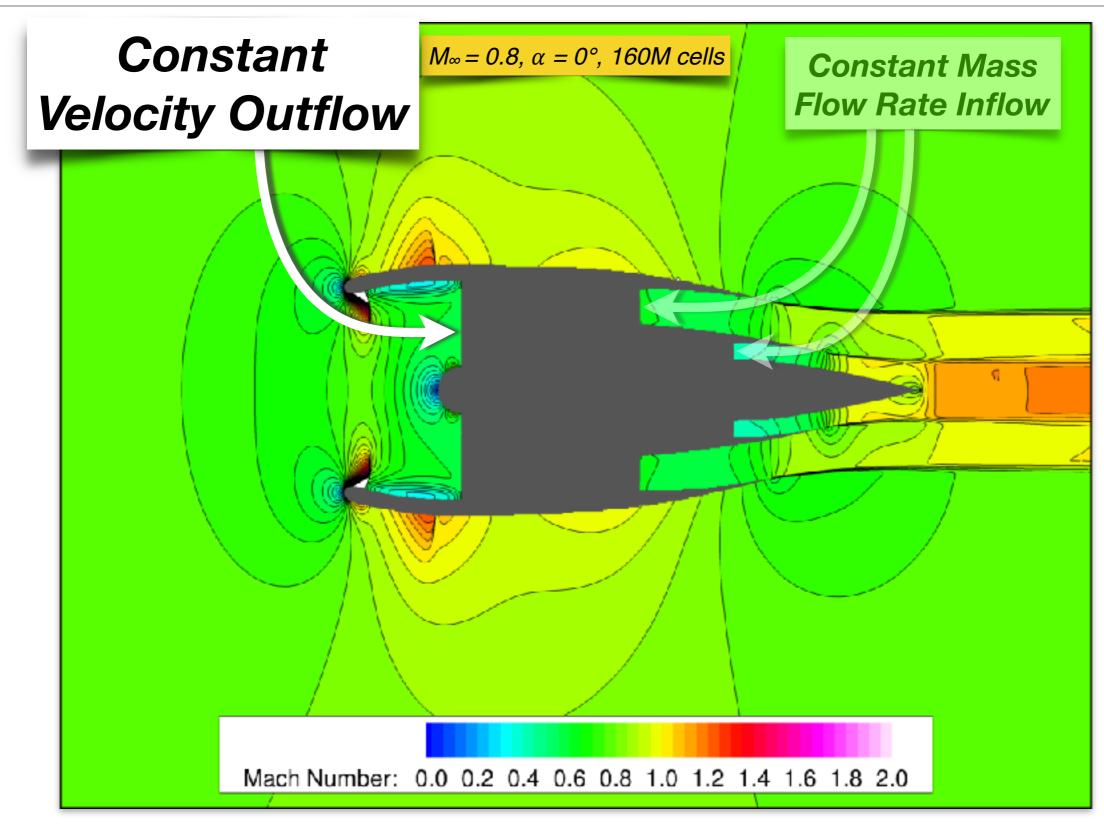
Turbofan - Example Solution





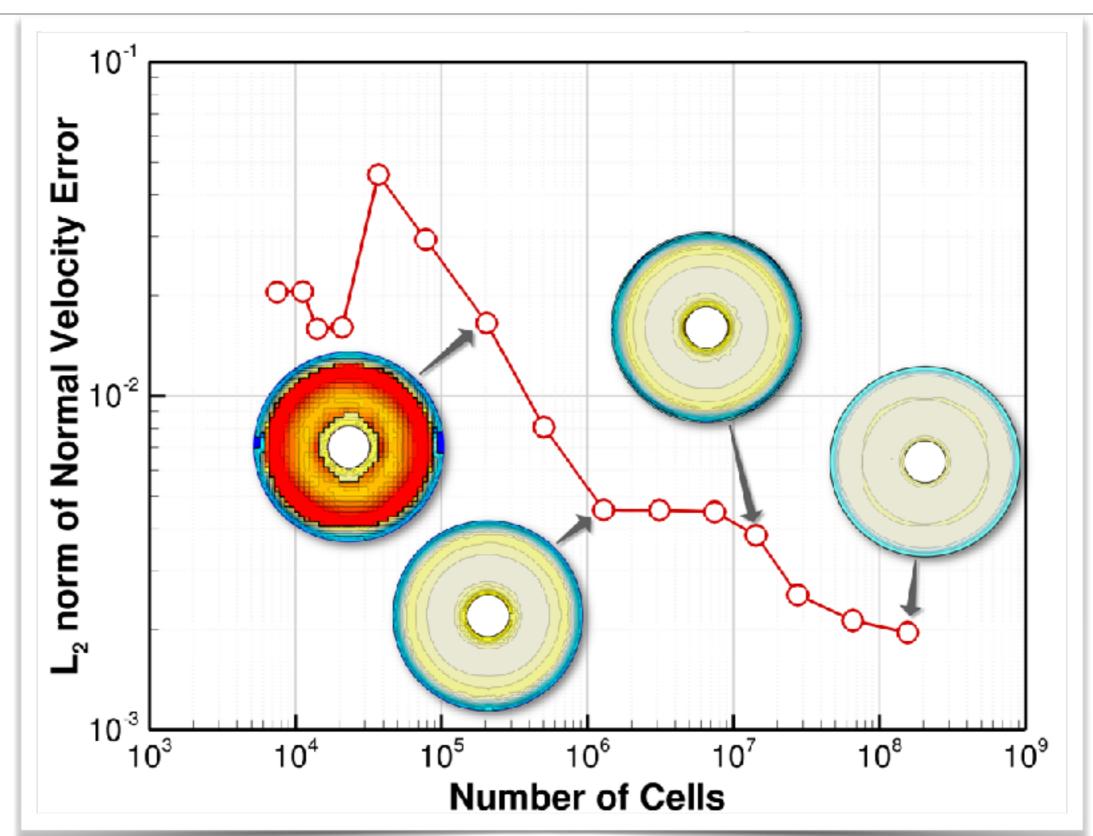
Turbofan - Example Solution





Constant Velocity B.C. Mesh Convergence

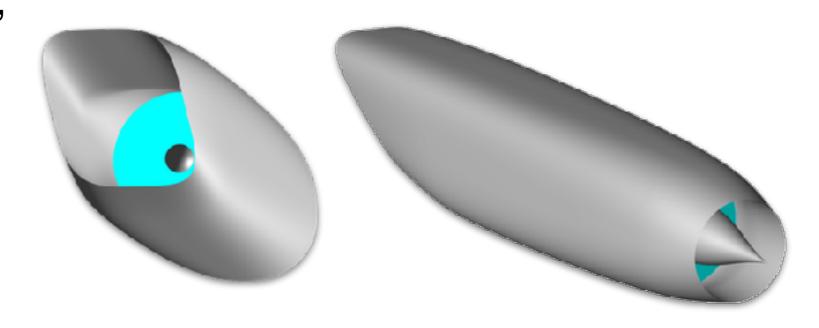


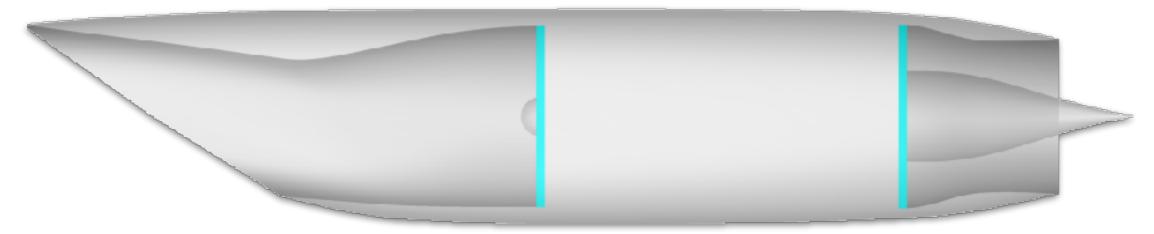


Turbojet in Supersonic Flow



- 2-D ramp inlet design for normal terminal shock
- Converging-diverging duct with cone nozzle
- Mach 1.5 freestream,
 1° angle of attack
- Outflow / Inflow boundary conditions applied to annuli

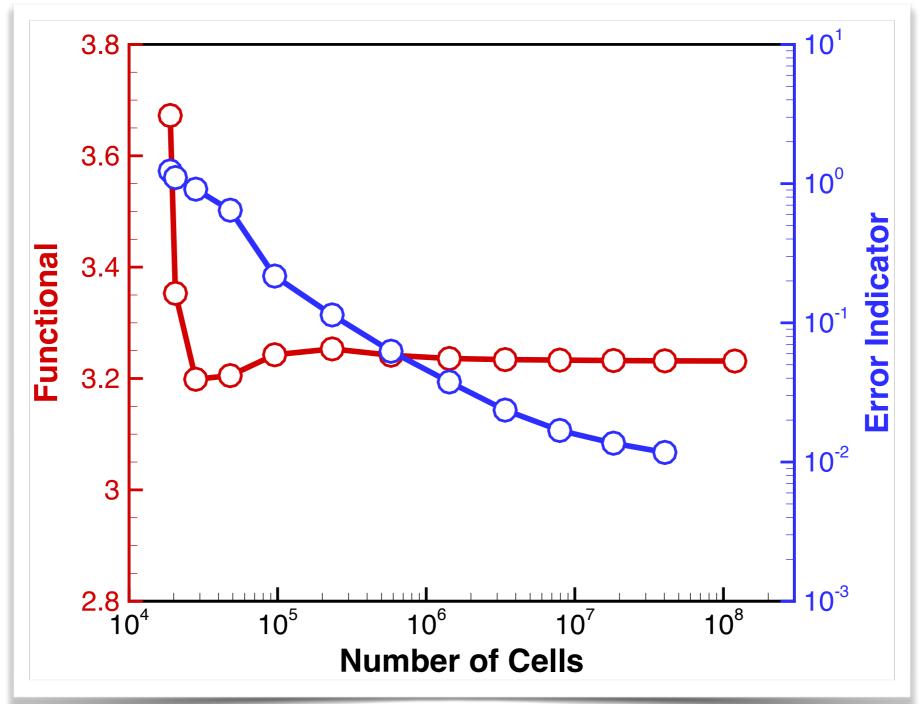




Turbojet - Mesh Convergence



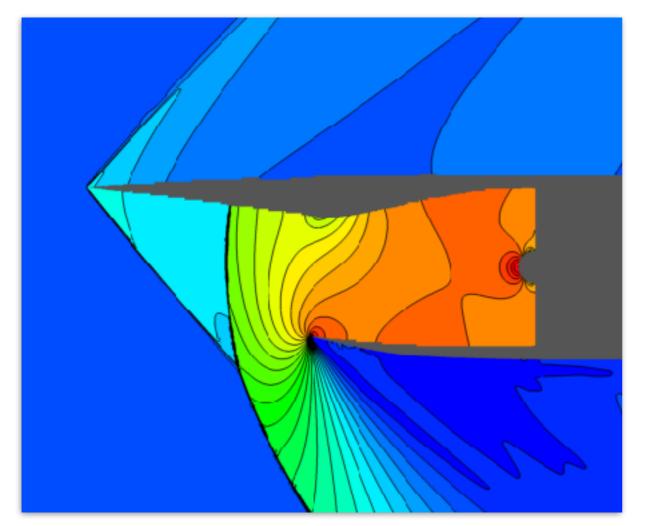
- Good convergence of functional (thrust + lift + plume sensor)
- Steady reduction in error estimate

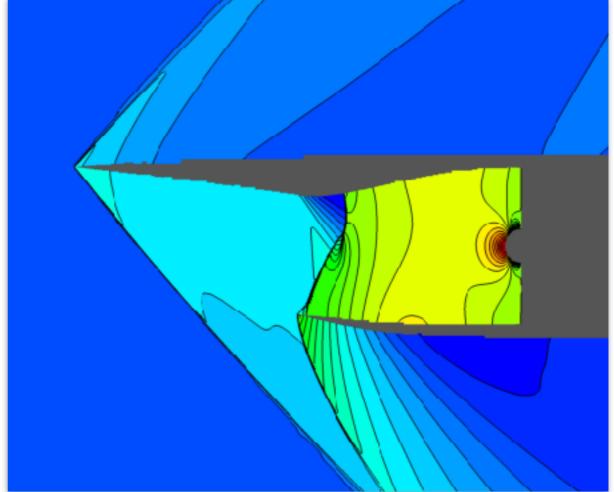


Supersonic Inlet - Mass Flow Rate



- Usually need to specify mass flow rate through an inlet
- Often desirable to match nozzle mass flow rate if modeled
- Highly nonlinear flow features can make mass flow rate steering difficult in supersonic and even transonic inlets

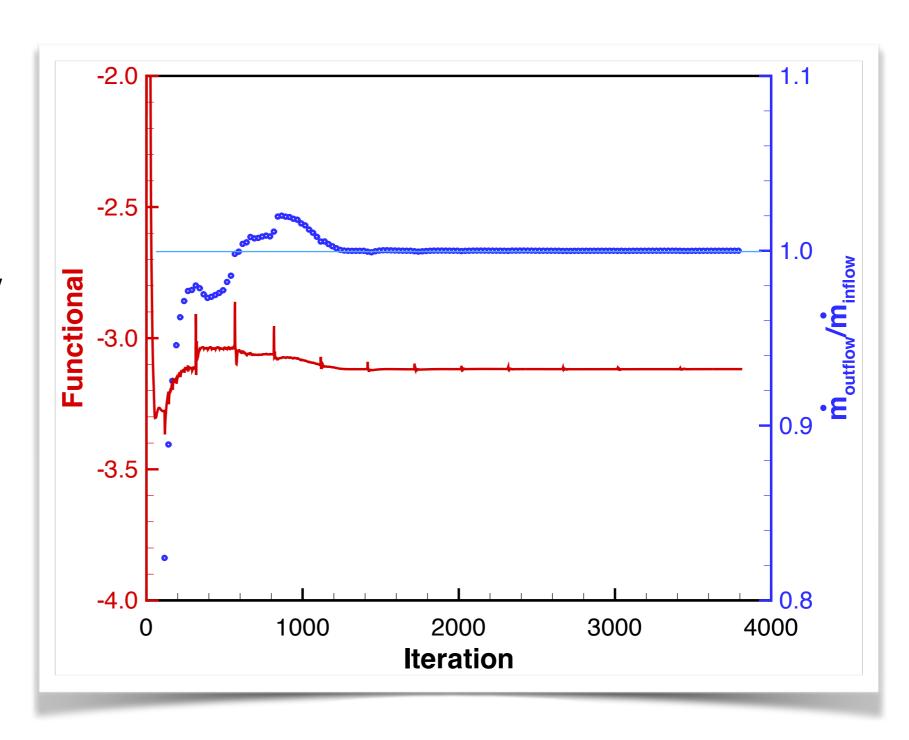




Turbojet - Mass Flow Rate Steering



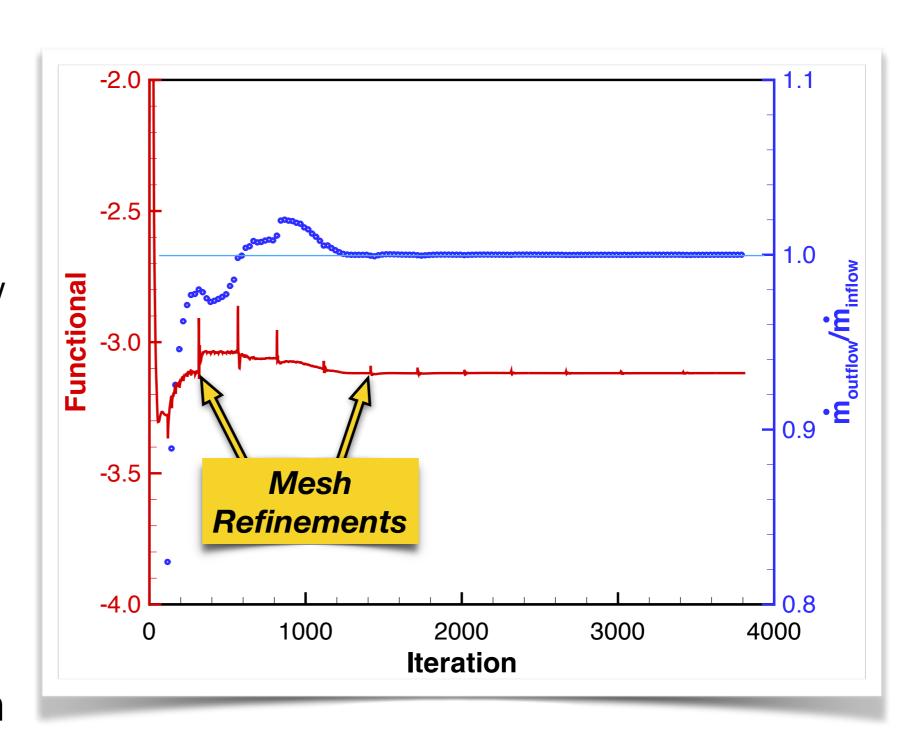
- Inflow mass flow rate (m_{inflow}) set through boundary condition
- Outflow mass flow rate (moutflow) steered to match
- Mass flow rate quickly converges and continues to converge through each refined mesh



Turbojet - Mass Flow Rate Steering



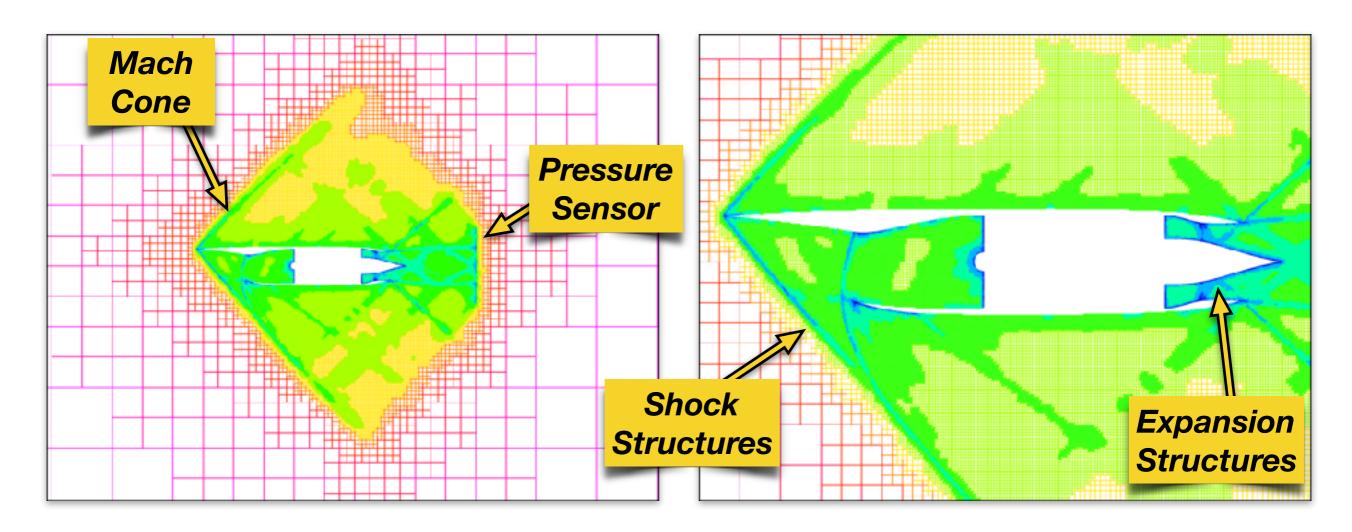
- Inflow mass flow rate (m
 inflow) set through boundary condition
- Outflow mass flow rate (moutflow) steered to match
- Mass flow rate quickly converges and continues to converge through each refined mesh



Turbojet - Adaptively Refined Mesh

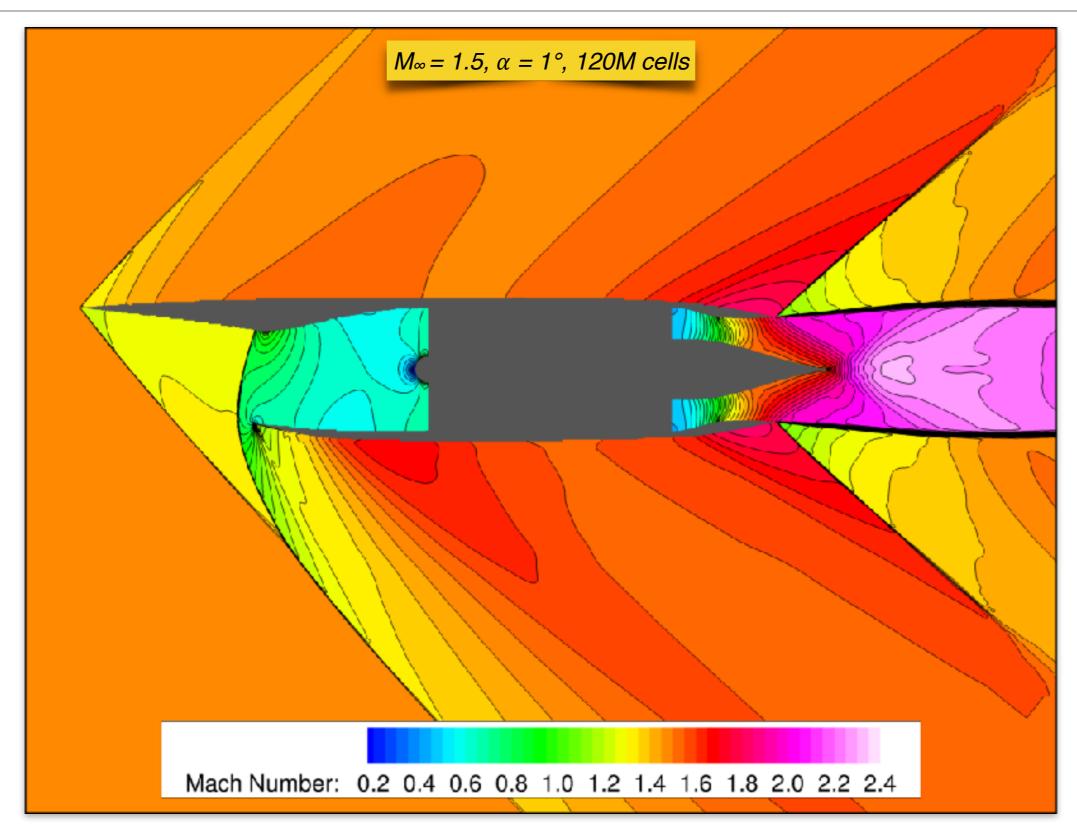


- Colors represent cells of same level of refinement
- Mesh was refined at surface, within Mach cone of influence, at shock and expansion structures, and at plume shear layer influencing pressure sensor



Turbojet - Matched Mass Flow Rates

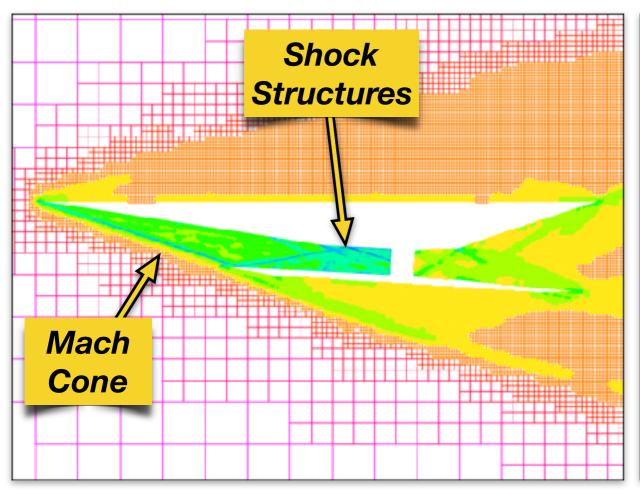


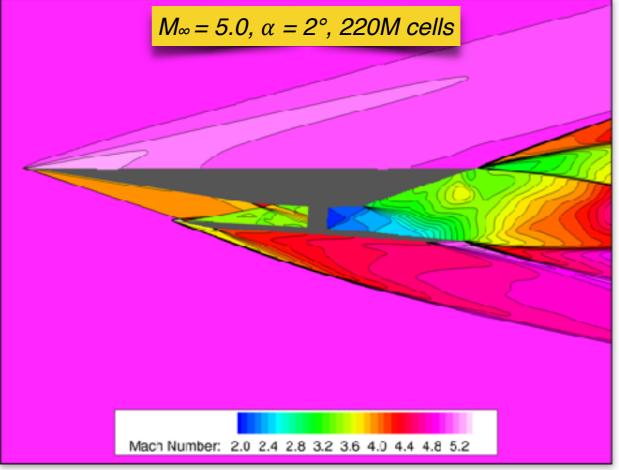


Scramjet in Hypersonic Flow



- Multiple ramp inlet and outlet, flow through burner remains supersonic
- Mach 5.0 freestream, 2° angle of attack
- Subsonic inflow / outflow boundary conditions not applicable
- Original full state with Riemann solver (SurfBC) boundary condition applied
- Mesh was refined at surface, within Mach cone of influence, shock and expansion structures, and plume shear layer influencing pressure sensor





29 DLRodriguez

Low Boom Supersonic Demonstrator



Main Exhaust

Nozzle

- Realistically complex geometry
- Mach 1.4 freestream,
 2.15° angle of attack
- 3 inlets and 3 exhausts



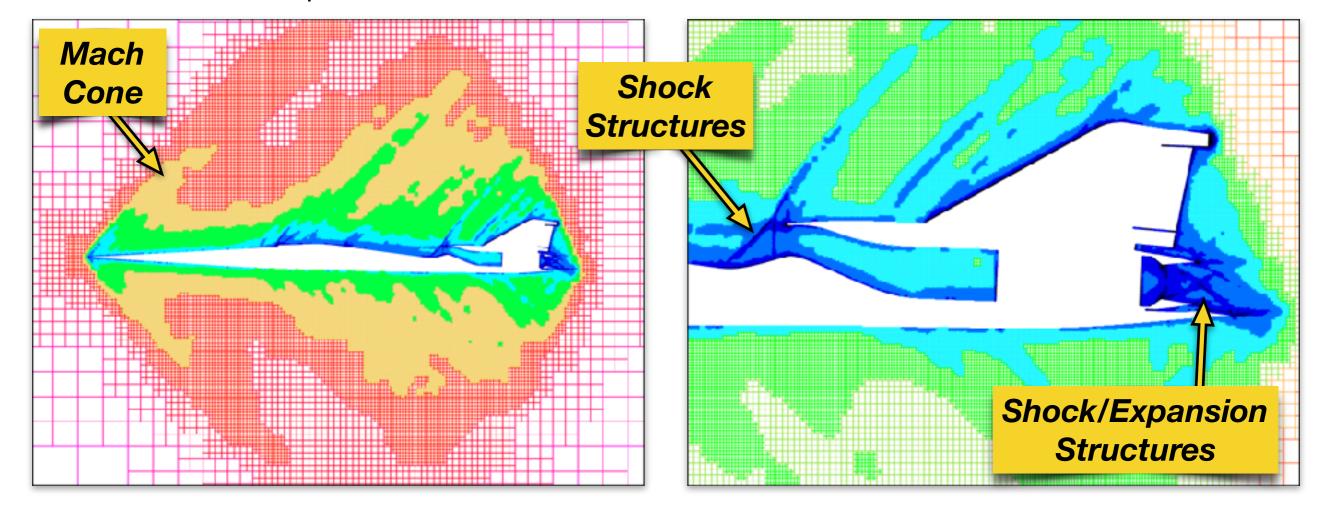
Tail Base

Vent

Low Boom Aircraft - Adaptively Refined Mesh

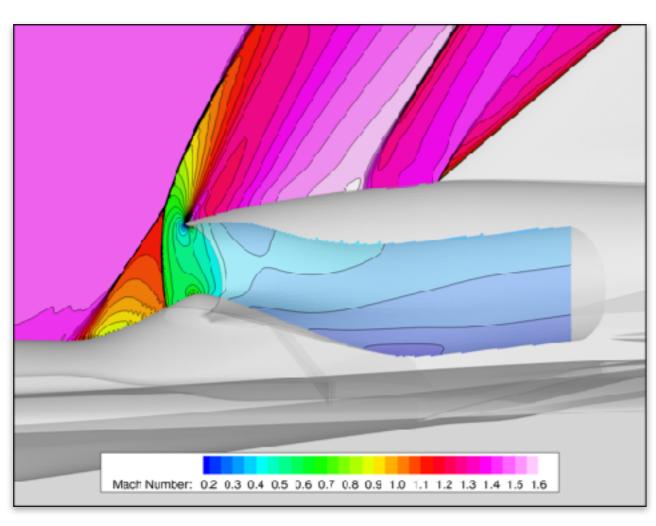


- Functional was aircraft drag
- Colors represent cells of same level of refinement
- Mesh was refined at surface, within Mach cone of influence, and at shock and expansion structures



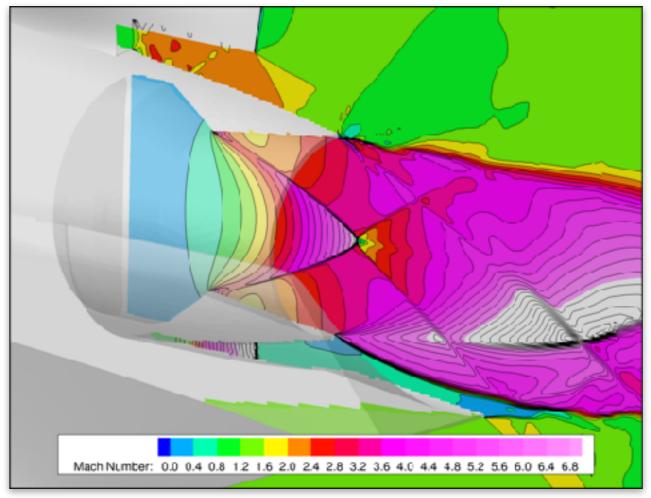
Low Boom Aircraft - Example Solution





 $M_{\infty} = 1.4$, $\alpha = 2.15^{\circ}$, 70M cells (half-body mesh)

- Underwing inlet geometry is not fully realized
- Safeguards were active in these inlets (solid wall to not allow reverse flow)



Summary and Ongoing Work



- Four new subsonic inflow/outflow boundary conditions implemented to improve modeling of propulsion systems
- Robust mass flow rate control implemented for both inflow and outflow
- Demonstrated on notional propulsion systems in flight regimes ranging from subsonic to hypersonic
 - adjoint-driven mesh refinement demonstrated with all propulsion boundary conditions
 - new boundary conditions verified mesh convergence studies on notional examples
- Demonstrated on realistically complex low boom aircraft
- Ongoing work
 - Implement additional functionals appropriate for propulsion systems
 - Extend design framework to include new propulsion boundary conditions and functionals

Acknowledgements



- NASA ARMD Commercial Supersonic Technology (CST)
 Project provided funding
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- Other colleagues in Computational Aerosciences Branch